

EURADOS → Training course

Evaluating uncertainty

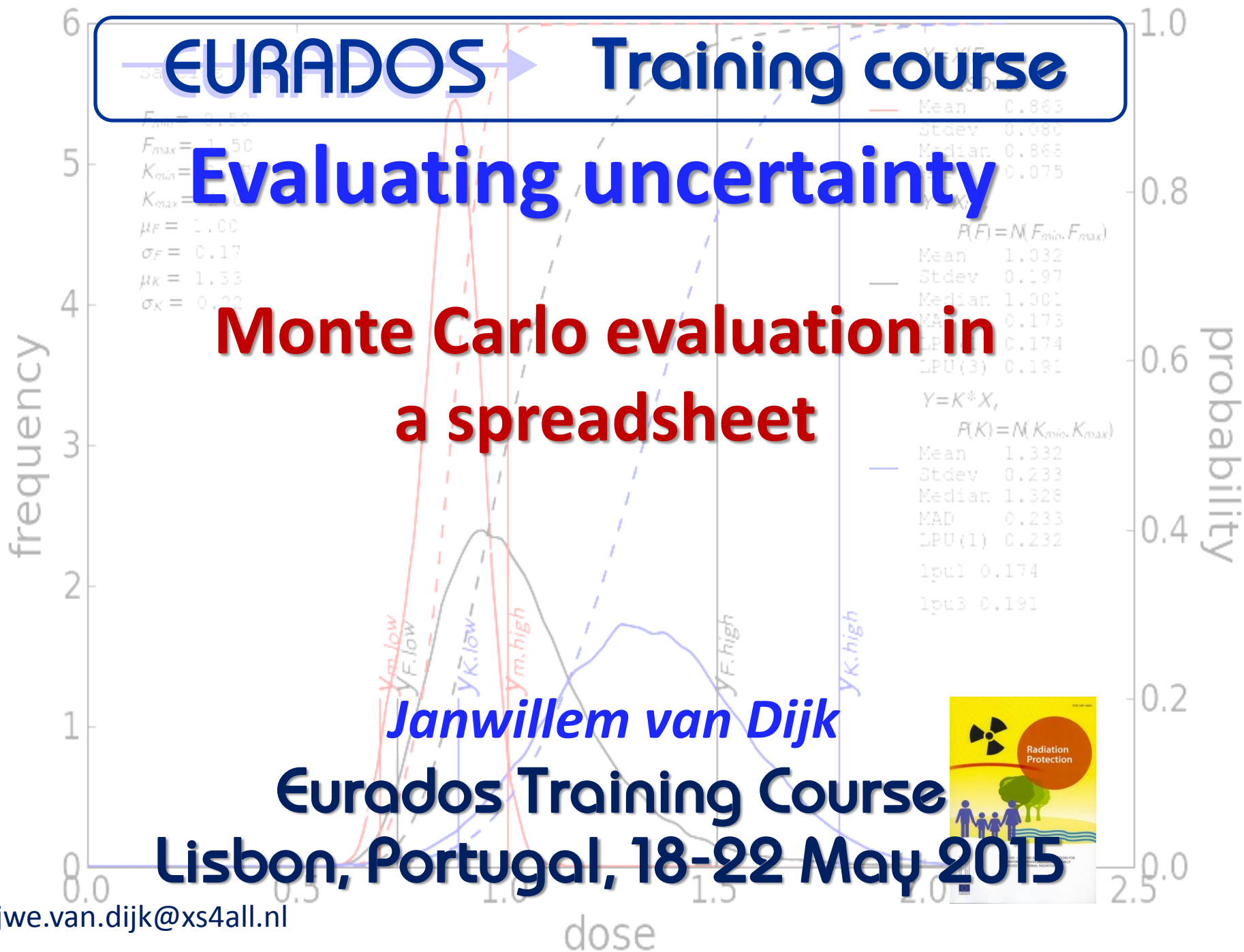
Monte Carlo evaluation in a spreadsheet

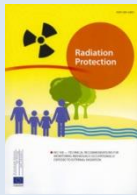
Janwillem van Dijk

Eurados Training Course

Lisbon, Portugal, 18-22 May 2015

jwe.van.dijk@xs4all.nl





mcm_example.xlsm,
mcm_example.ods

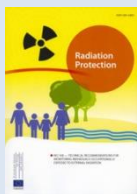
$$x = f_R f_{\text{Det}} (f_{E,\alpha} H_{\text{True}} + f_{\text{Bg}} h_{\text{Bg}}) + z$$

$$y = \frac{x - Z}{F_R F_{E,\alpha} F_{\text{Det}}} - \frac{F_{\text{Bg}}}{F_{E,\alpha}} Y_{\text{Bg}}$$

$\hat{x}$: the signal you will see from the reader

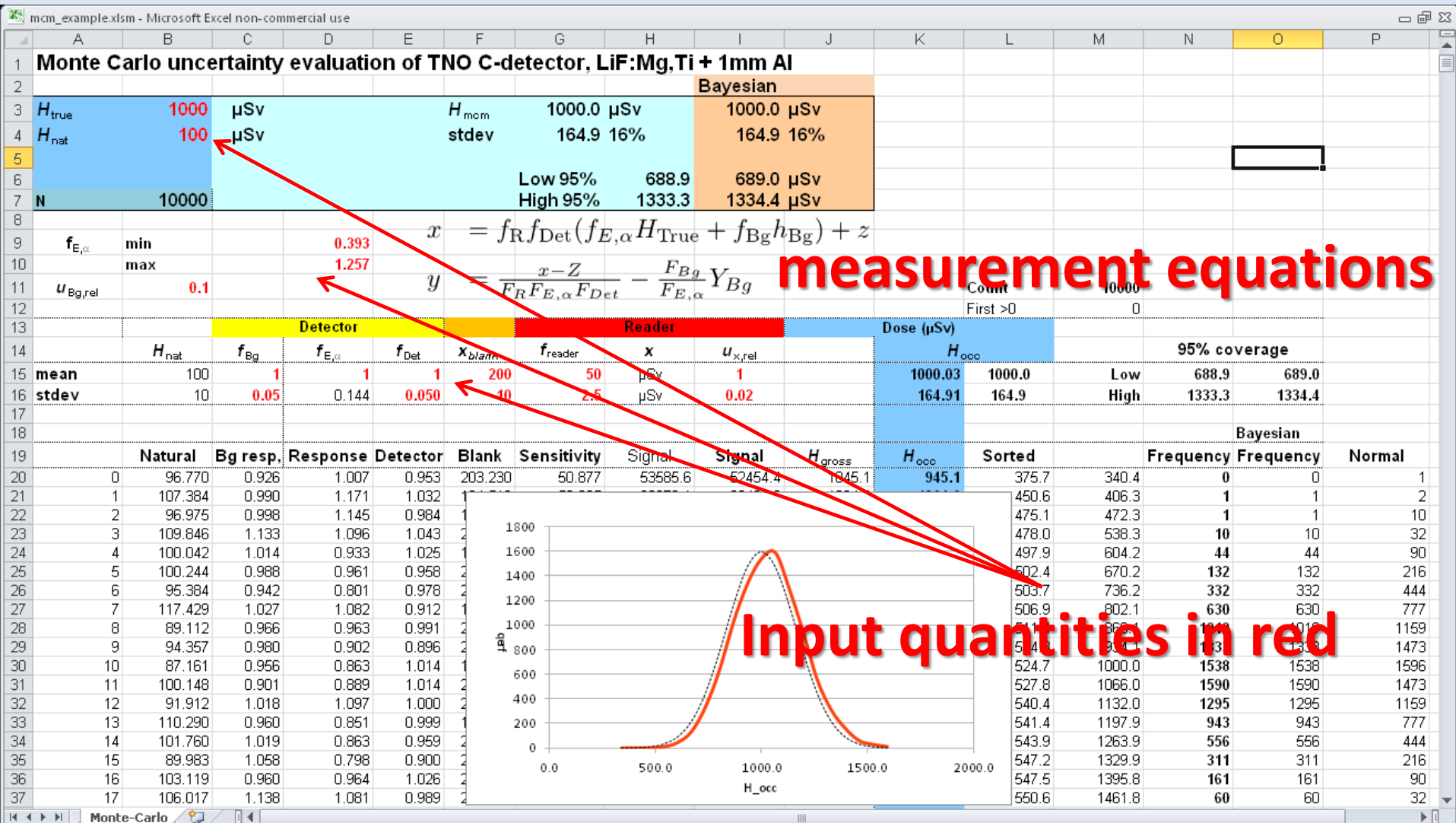
$\hat{y}$: the dose you will report

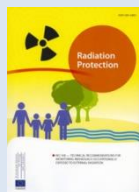
Symbols in capital are expectations



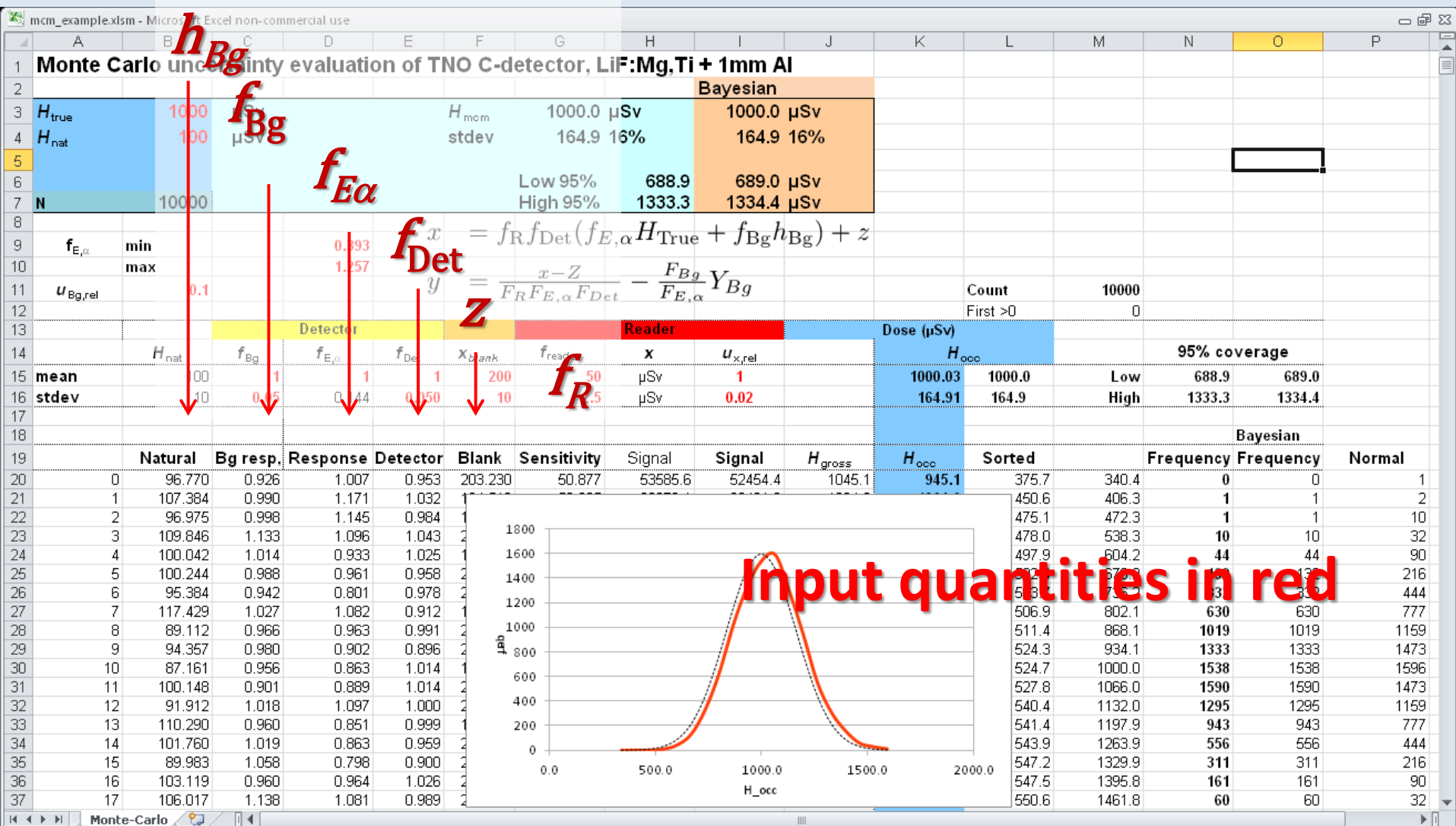
Evaluating uncertainty

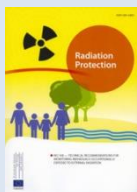
EURADOS





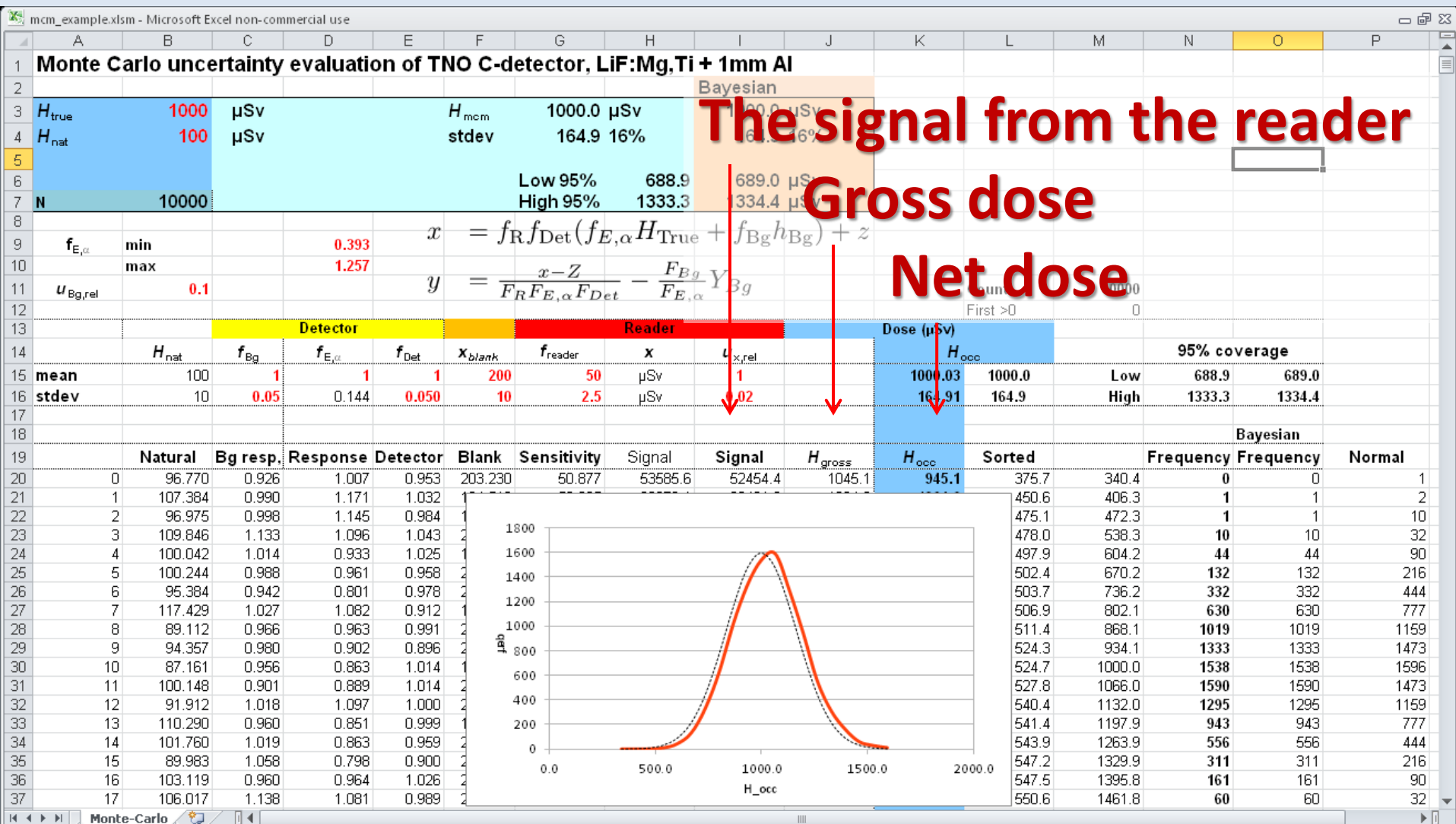
Evaluating uncertainty





Evaluating uncertainty

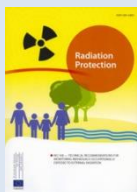
EURADOS



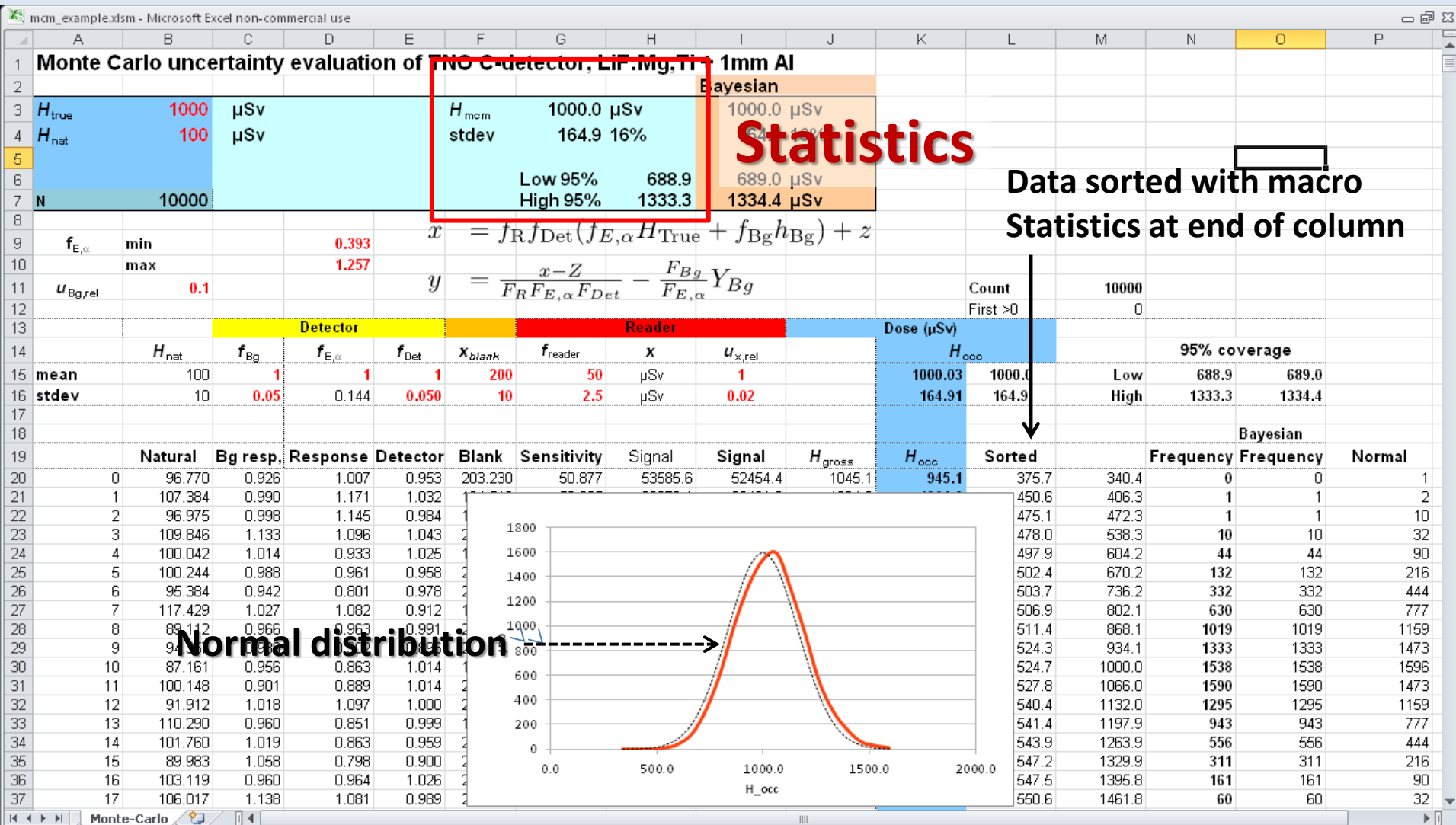
The signal from the reader

Gross dose

Net dose

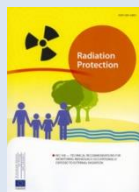


Evaluating uncertainty

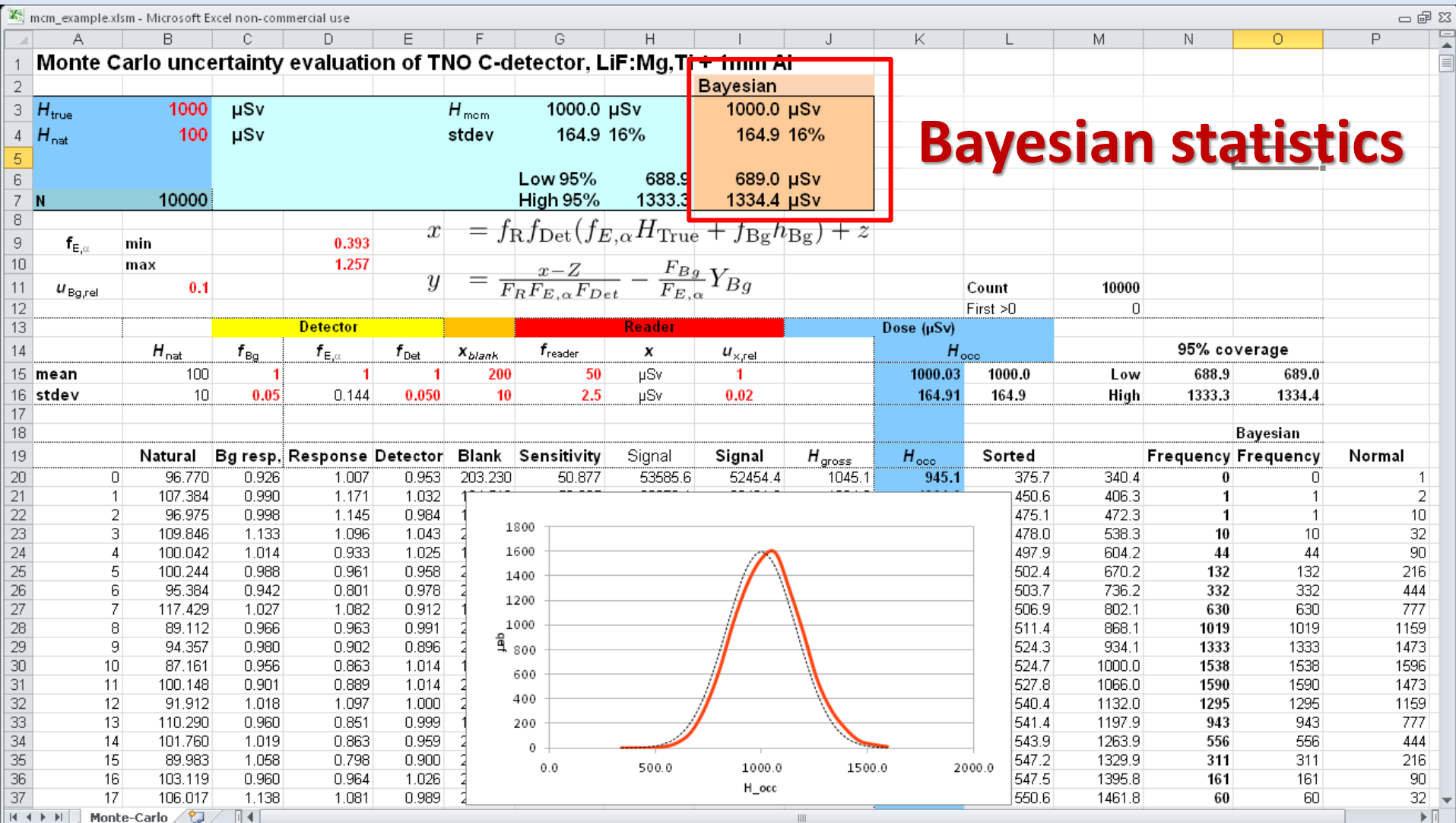


Statistics

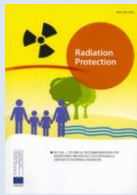
Data sorted with macro
 Statistics at end of column



Evaluating uncertainty



Bayesian statistics



MCM number of samples needed

The sheet works with 10,000 samples

Recalculation (Press F9) will show different results

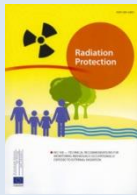
The figure changes shape

10,000 samples is in general far to few

IEC TR 62461:2015 recommends 1,000,000

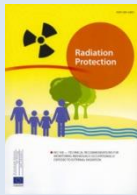
The JCGM gives an adaptive procedure

van Dijk, J.W.E. *Measurement models for passive dosimeters in view of uncertainty evaluation using Monte Carlo method*, Radiat. Prot. Dosim. 162(4), 438-445 (2014)



MCM number of samples needed

**My experience for the current type of problems:
300,000-500,000 will do
except where the measurand distribution is
very skewed**



Characteristic limits

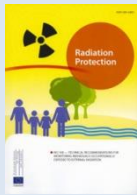
Decision threshold

The value above which you can decide that a dose above background level is observed

Detection limit

The smallest true value of the dose that can be detected with the dosimeter

ISO 11929:2010, *Determination of the detection limit and decision threshold for ionizing radiation measurements*



Characteristic limits

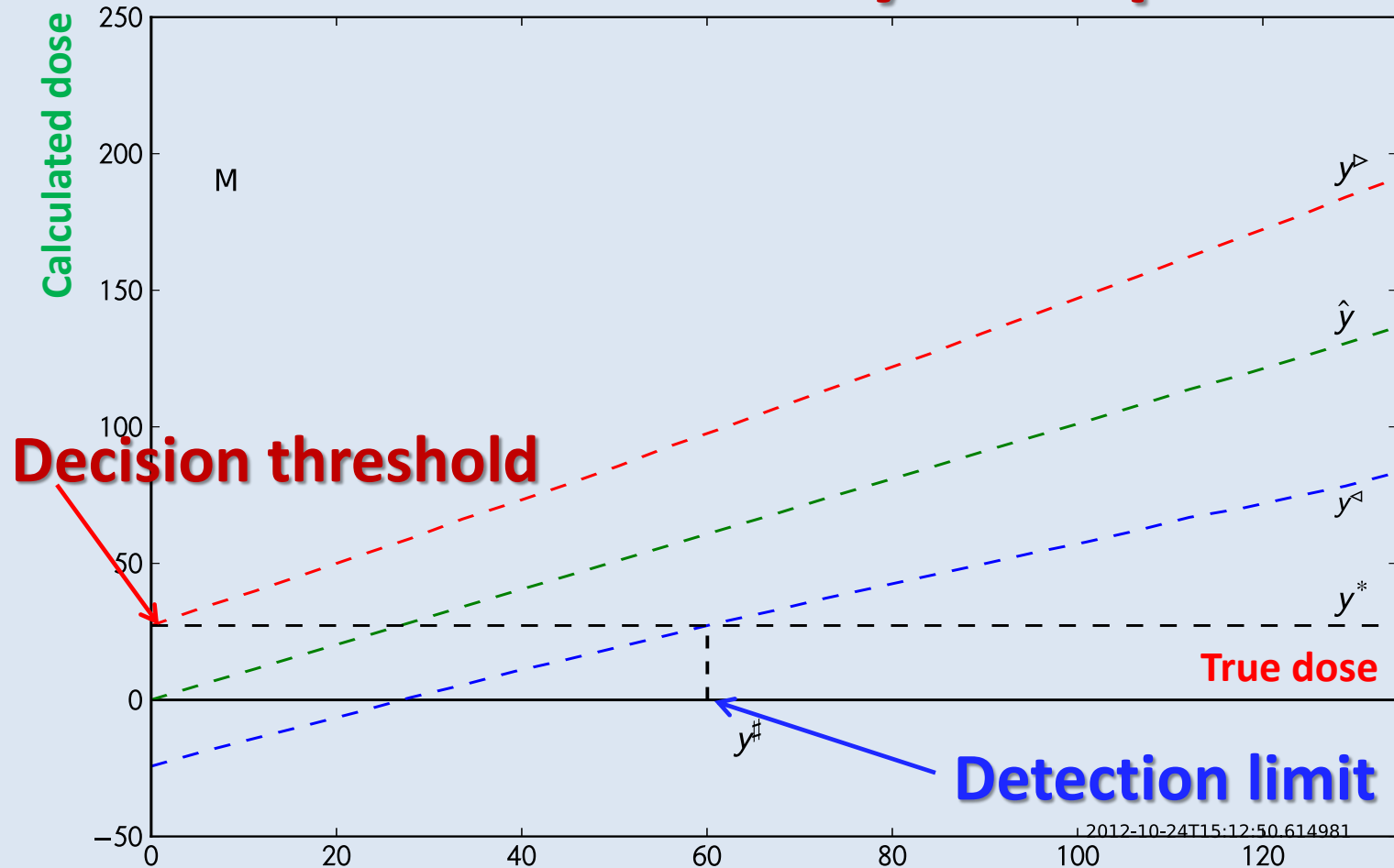
Rule of thumb:

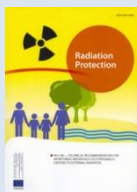
$$y^* \simeq 1.7u_y \mid y = 0.0$$

$$y^\# \simeq 3.3u_y \mid y = 0.0$$

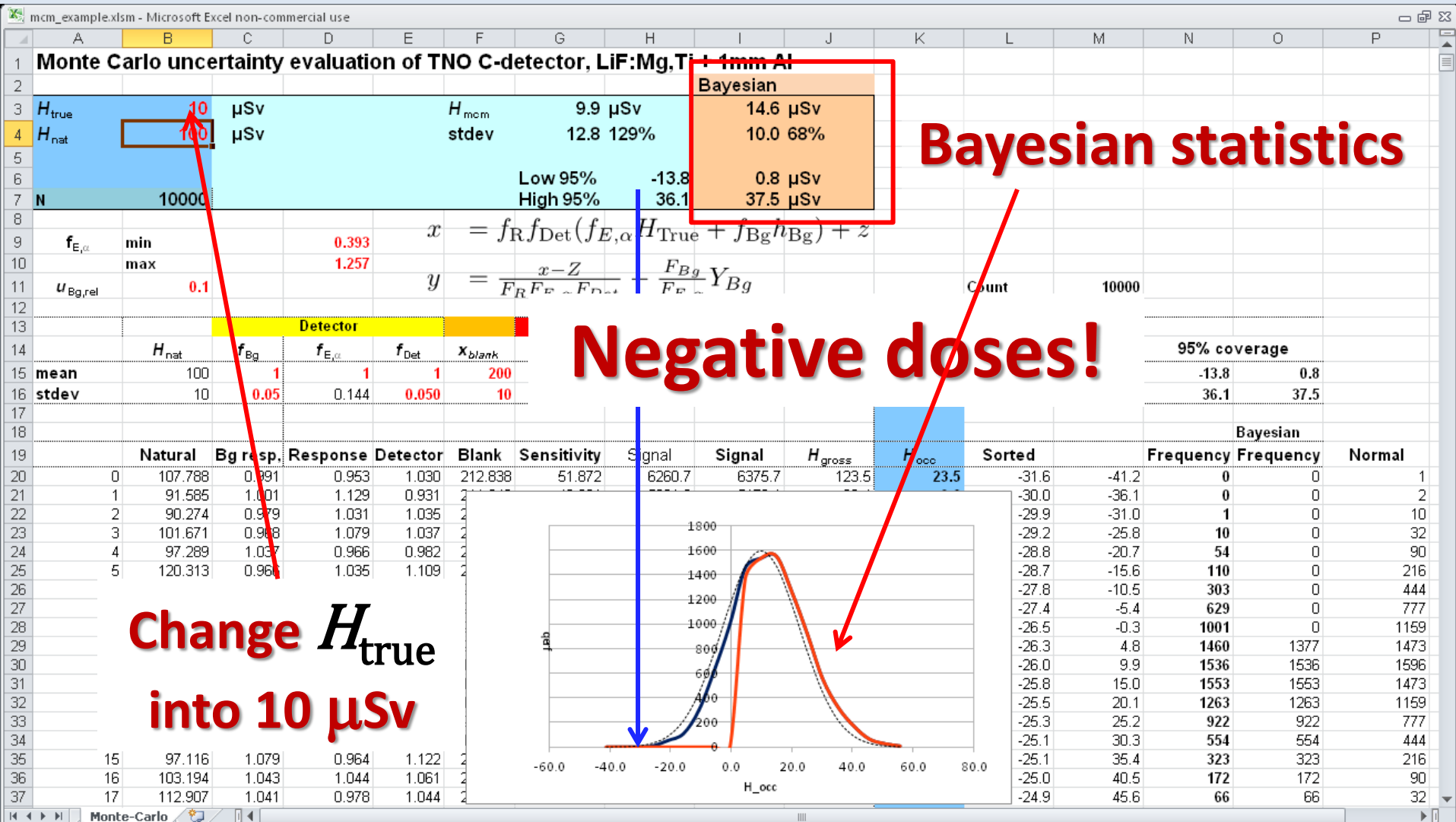
L.A. Curry, *Uncertainties in measurements close to the detection limit: Detection and quantification capabilities in IAEA Tecdoc 1401 (9-34)*

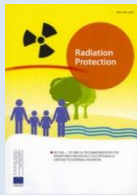
Characteristic limits by interpolation





Evaluating uncertainty





MCM and Bayes

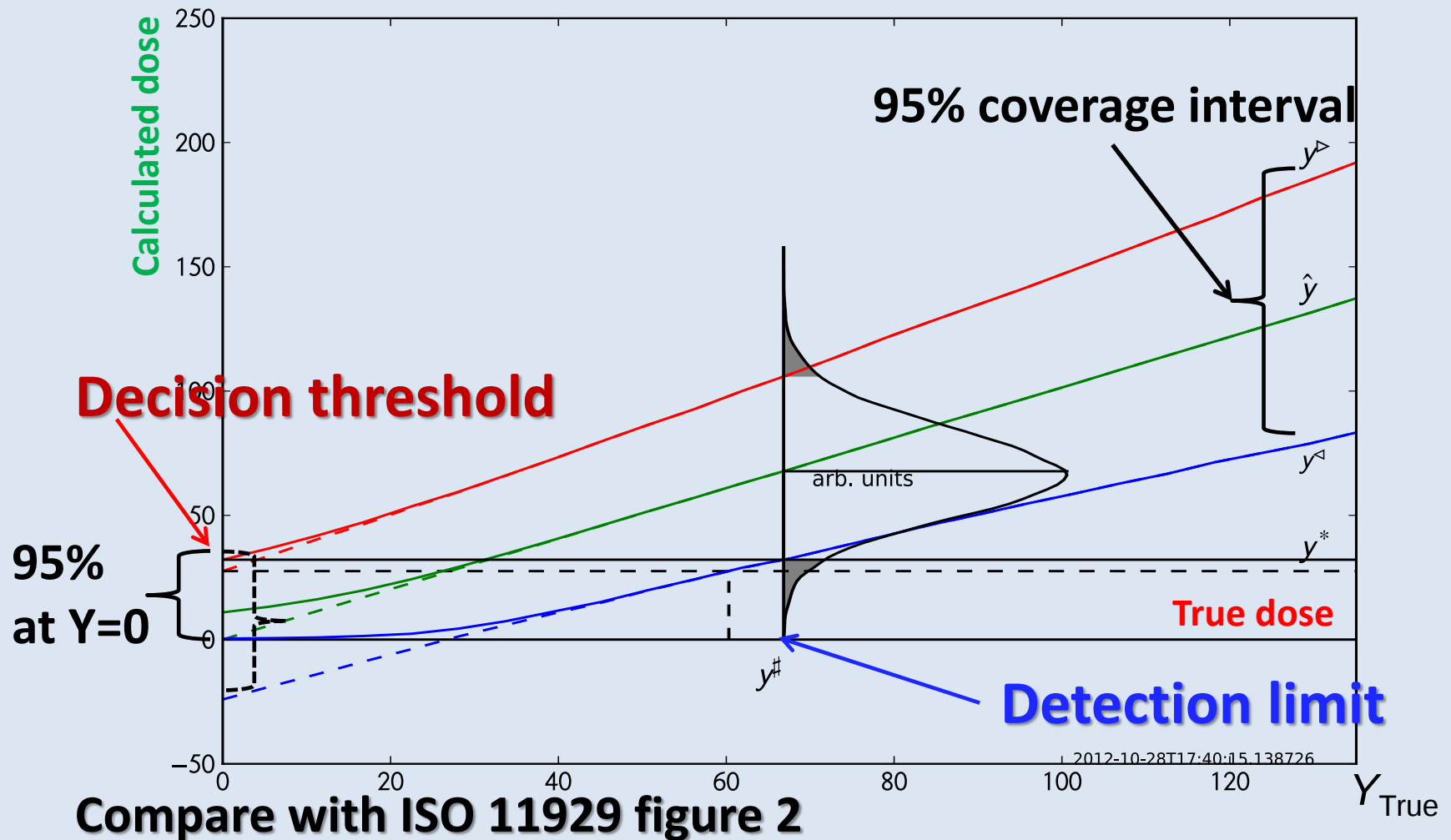
Using Mont Carlo Bayesian statistics for

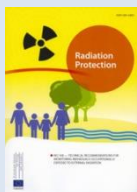
prior: $P(y < 0) = 0$

is achieved by rejecting all negative samples

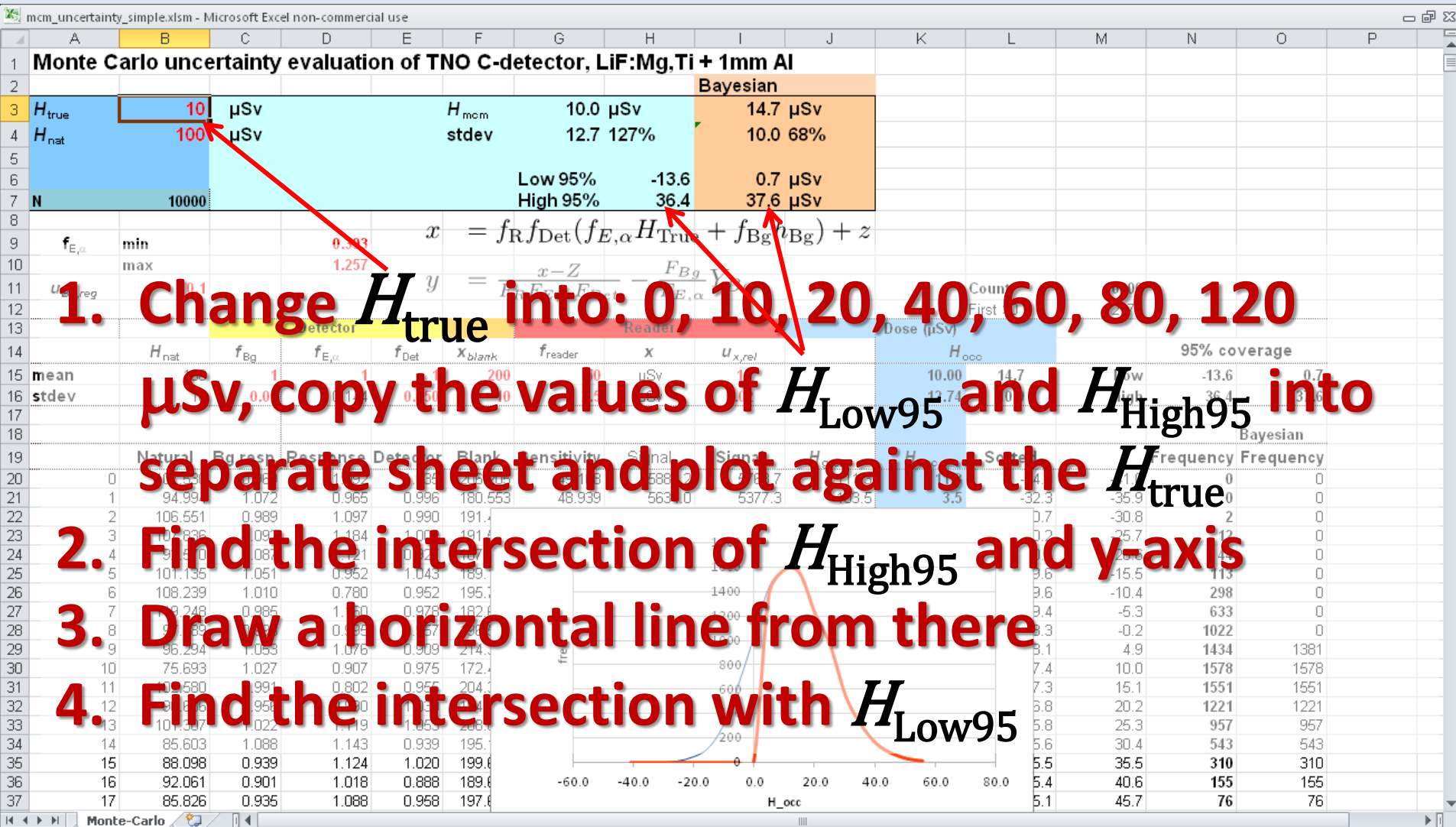
C. Elster, *Calculation of uncertainty in the presence of prior knowledge*. Metrologia 44 111-116 (2007)

Characteristic limits by interpolation

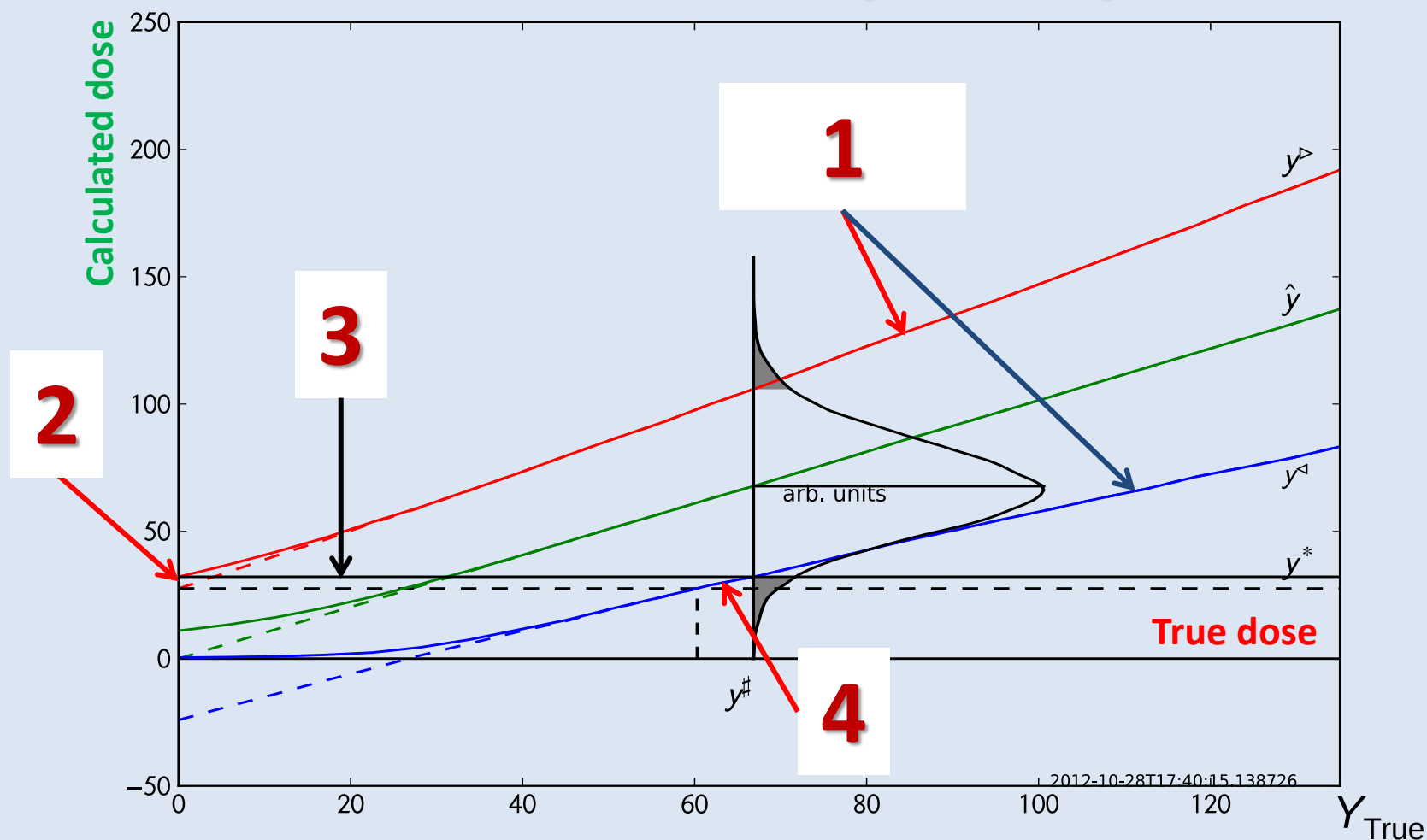




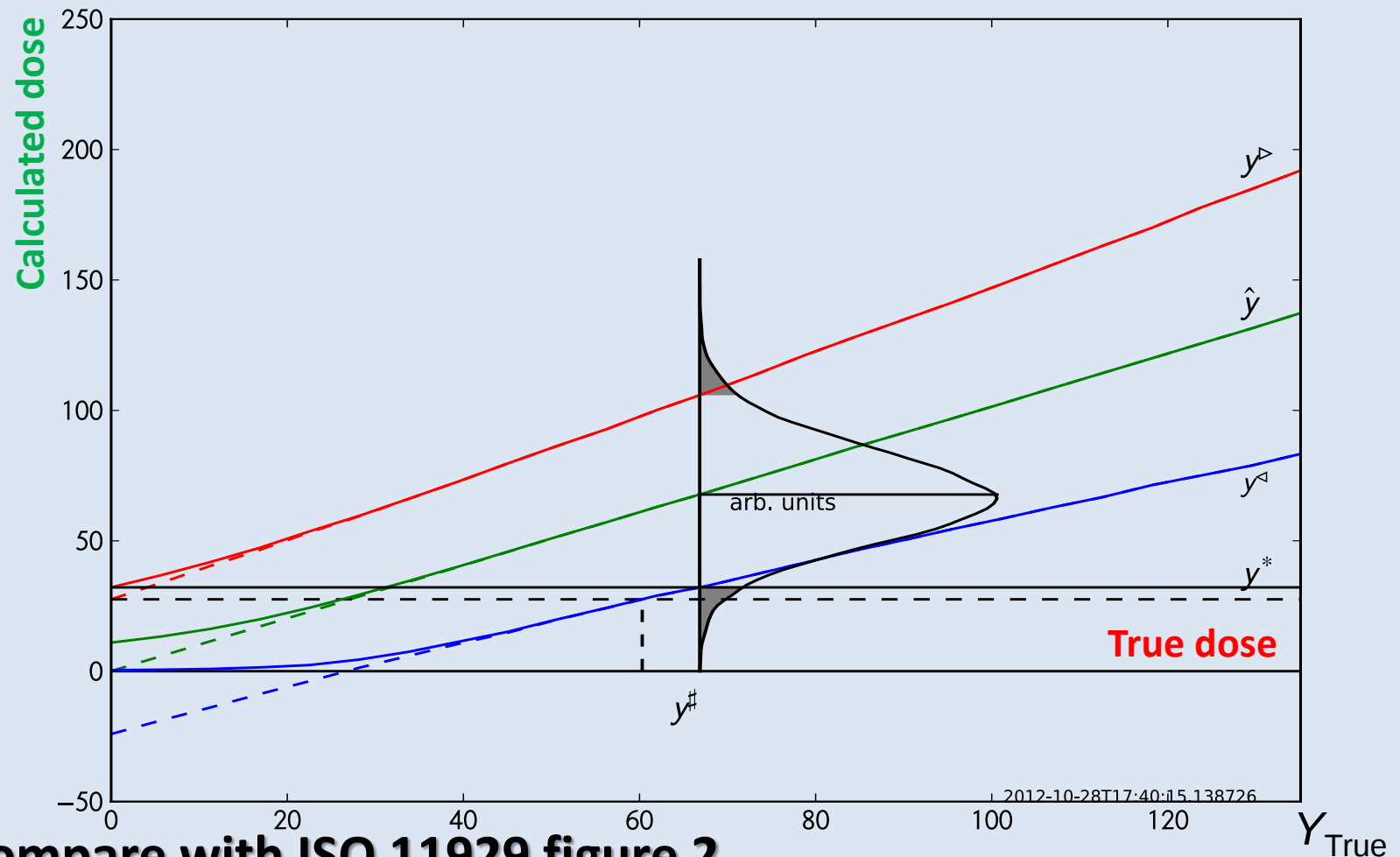
Evaluating uncertainty



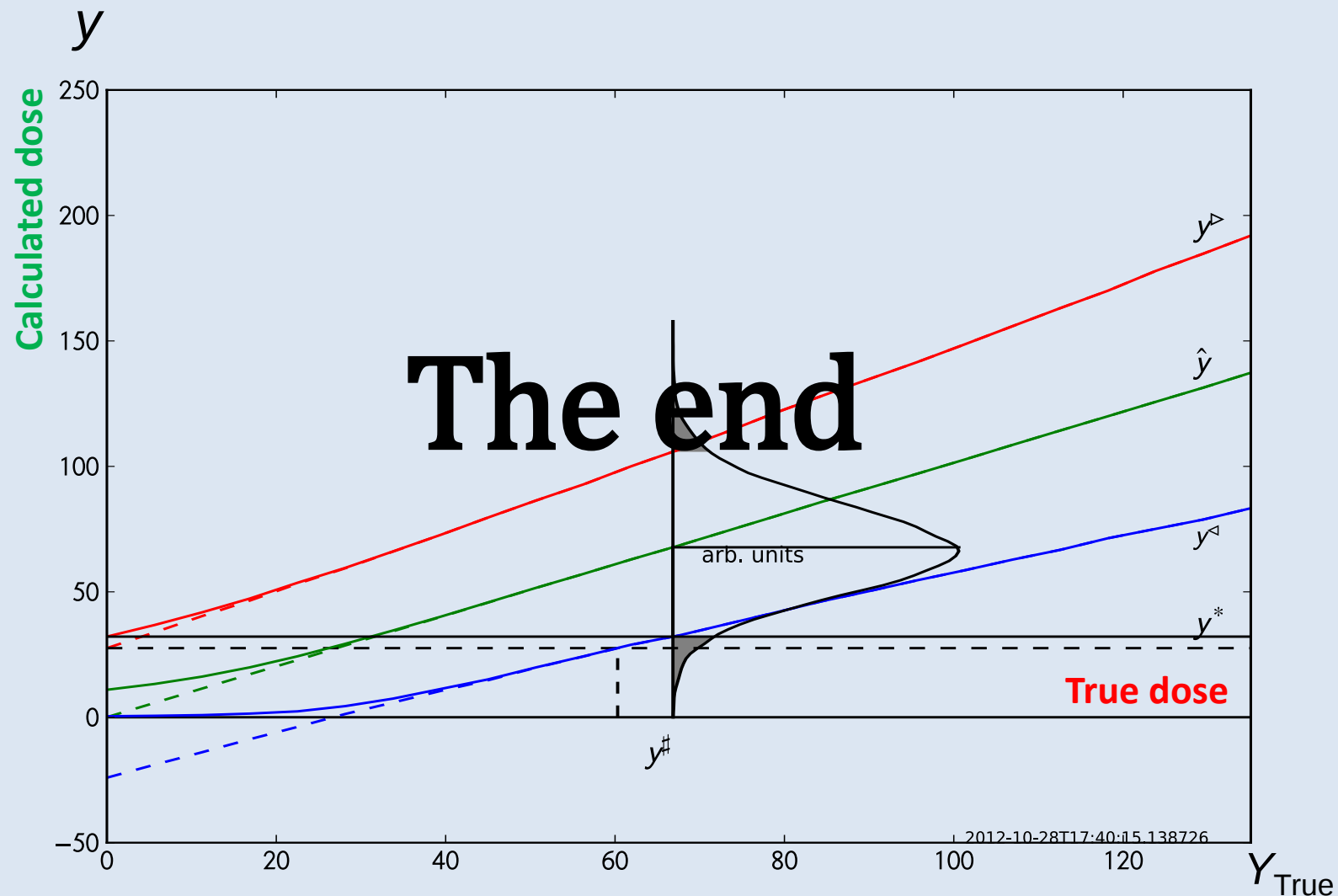
Characteristic limits by interpolation

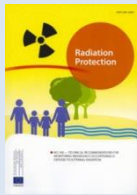


Characteristic limits by interpolation



Compare with ISO 11929 figure 2





Important guiding documents

Joint Committee on Guides in Metrology

Guide to the expression of uncertainties in measurement and supplements

<http://www.bipm.org/en/publications/guides/gum.html> *)

European Commission

Technical Recommendations for Monitoring Individuals Occupationally Exposed to Ionizing Radiation

<http://ec.europa.eu/energy/sites/ener/files/documents/160.pdf> *)

ICRU Report 76

Measurement quality assurance for ionizing radiation dosimetry

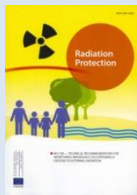
<http://www.icru.org>

IEC TR 62461

Radiation Protection Instrumentation – Determination of uncertainty

http://webstore.iec.ch/preview/info_iec62461%7Bed2.0%7Den.pdf

*) Document can be downloaded for free



Some Monte Carlo literature

J. W. E. van Dijk, *Measurement models for passive dosimeters in view of uncertainty evaluation using the Monte Carlo method*. Radiat Prot Dosimetry (2014) 162 (4): 438-445

H. Stadtmann and C. Hranitzky, *Uncertainty assessment of a two element LiF:Mg,Ti TL personal dosimeter using Monte-Carlo techniques*. Radiat Prot Dosimetry (2011) 144 (1-4): 67-71

R. Behrens, *Uncertainties in external dosimetry: analytical vs. Monte Carlo method*. Radiat Prot Dosimetry (2010) 138 (4): 346-352

J. W. E. van Dijk, *Developments in uncertainty analysis for individual monitoring*. Radiat Prot Dosimetry (2011) 144 (1-4): 56-61

J. W. E. van Dijk, *Evaluating the uncertainty in measurement of occupational exposure with personal dosimeters*. Radiat Prot Dosimetry (2007) 125 (1-4): 387-394

J. W. E. van Dijk, *Uncertainties in personal dosimetry for external radiation: a Monte Carlo approach*. Radiat Prot Dosimetry (2006) 121 (1): 31-38

Maurice Cox, Peter Harris, Gyeonghee Nam, and David Thomas, *The use of a Monte Carlo method for uncertainty calculation, with an application to the measurement of neutron ambient dose equivalent rate*. Radiat Prot Dosimetry (2006) 121 (1): 12-23

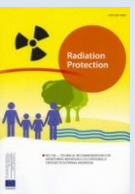
Table B.1 – Example of an uncertainty budget for a photon dose measurement with a passive dosimetry system according to IEC 62387-1:2007 and low level of consideration of the workplace conditions, see text for details

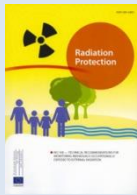
Quantity	Best estimate	Absolute standard uncertainty	Distribution; mean value, x ; half-width, a	Sensitivity coefficient	Uncertainty contribution to output quantity
N_0	1.00	$0.05\sqrt{6} = 0,020\ 4$	Triangular; $x = 1,0$; $a = 0,05$	10 mSv	0,20 mSv
K_n	1.00	$0.10\sqrt{3} = 0,057\ 7$	Rectangular; $x = 1,0$; $a = 0,1$	10 mSv	0,58 mSv
$K_{E,\square\phi}$	1.00	$0.40/3 = 0,133$	Gaussian; $x = 1,0$; $a = 0,4$	10 mSv	1,33 mSv
K_{add}	1.00	0	Rectangular; $x = 1,0$; $a = 0,0$	10 mSv	0,0 mSv
K_{temp}	1.00	$0.20/3 = 0,066\ 7$	Gaussian; $x = 1,0$; $a = 0,20$	10 mSv	0,67 mSv
K_{light}	1.00	$0.1/3 = 0,033\ 3$	Gaussian; $x = 1,0$; $a = 0,10$	10 mSv	0,33 mSv
K_{dip}	1.00	$0.1/3 = 0,033\ 3$	Gaussian; $x = 1,0$; $a = 0,10$	10 mSv	0,33 mSv
K_{stab}	1.00	$0.1/3 = 0,033\ 3$	Gaussian; $x = 1,0$; $a = 0,10$	10 mSv	0,33 mSv
K_{tempR}	1.00	$0.1/3 = 0,033\ 3$	Gaussian; $x = 1,0$; $a = 0,10$	10 mSv	0,33 mSv
K_{lightR}	1.00	$0.1/3 = 0,033\ 3$	Gaussian; $x = 1,0$; $a = 0,10$	10 mSv	0,33 mSv
K_{pow}	1.00	$0.1/3 = 0,033\ 3$	Gaussian; $x = 1,0$; $a = 0,10$	10 mSv	0,33 mSv
G	10 mSv	$0.05 \times 10\text{ mSv} = 0,50\text{ mSv}$	Gaussian with one reading; $x = 10,0\text{ mSv}$; $a = 1,50\text{ mSv}$	1.00	0,50 mSv
$DEM_{C,1}$	0 mSv	$0.7 \times 0,1\text{ mSv}/3 = 0,023\ 3\text{ mSv}$	Gaussian; $x = 0,0\text{ mSv}$; $a = 0,07\text{ mSv}$	-1.00	0,023 mSv
$DEM_{C,2}$	0 mSv	$0.7 \times 0,1\text{ mSv}/3 = 0,023\ 3\text{ mSv}$	Gaussian; $x = 0,0\text{ mSv}$; $a = 0,07\text{ mSv}$	-1.00	0,023 mSv
$DEM_{C,3}$	0 mSv	$0.7 \times 0,1\text{ mSv}/3 = 0,023\ 3\text{ mSv}$	Gaussian; $x = 0,0\text{ mSv}$; $a = 0,07\text{ mSv}$	-1.00	0,023 mSv
$DEM_{C,4}$	0 mSv	$0.7 \times 0,1\text{ mSv}/3 = 0,023\ 3\text{ mSv}$	Gaussian; $x = 0,0\text{ mSv}$; $a = 0,07\text{ mSv}$	-1.00	0,023 mSv
$DEM_{C,5}$	0 mSv	$0.7 \times 0,1\text{ mSv}/3 = 0,023\ 3\text{ mSv}$	Gaussian; $x = 0,0\text{ mSv}$; $a = 0,07\text{ mSv}$	-1.00	0,023 mSv
$DEM_{C,6}$	0 mSv	$0.7 \times 0,1\text{ mSv}/3 = 0,023\ 3\text{ mSv}$	Gaussian; $x = 0,0\text{ mSv}$; $a = 0,07\text{ mSv}$	-1.00	0,023 mSv
$DEM_{C,7}$	0 mSv	$0.7 \times 0,1\text{ mSv}/3 = 0,023\ 3\text{ mSv}$	Gaussian; $x = 0,0\text{ mSv}$; $a = 0,07\text{ mSv}$	-1.00	0,023 mSv
D_{dipo}	0 mSv	$0.7 \times 0,1\text{ mSv}/3 = 0,023\ 3\text{ mSv}$	Gaussian; $x = 0,0\text{ mSv}$; $a = 0,07\text{ mSv}$	-1.00	0,023 mSv
$H_p(10)$	10,0 mSv	1,9 mSv (19 %)	(Analytical method)		

*) Taken with permission from TR 62461 IEC:2014-08 45B final draft.
Not to be used for reference purposes.

Evaluating uncertainty

IEC TR 62461 Table B1





The law of propagation of uncertainty, LPU, is based on the Taylor series development.

The measurand is for a value of the input quantity that slightly varies from the true value, approximated by a first degree Taylor series truncated after the 1st degree.

See NPL document ***dem_es11.pdf*** Chapter 6

True value Small deviation due to uncertainty

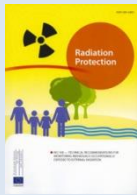
$$\begin{aligned} y &= f(x) \\ y_{\Delta} &= f(x + \Delta) \\ &= f(x) + \frac{\partial f(x)}{\partial x} \Delta + \frac{\frac{\partial^2 f(x)}{\partial x^2}}{2!} \Delta^2 + \dots \end{aligned}$$

Red arrows indicate the mapping from the text above to the equation: from "True value" to x , from "Small deviation due to uncertainty" to Δ , and from "Small deviation due to uncertainty" to the Δ^2 term.

Negligible

$\frac{\partial^2 f(x)}{\partial x^2} \Delta^2 + \dots$

Sensitivity coefficient



The variance of the joint distribution of a series of normal distributions is the sum of the variances of the individual distributions.

Adding the squares of the product of sensitivity coefficient and standard uncertainty gives the variance in the measurand.

$$v_x = \left(\frac{\partial f(x)}{\partial x} u_x \right)^2$$

Assumptions:

The higher degree terms of the Taylor series can be neglected ($\sim$ LPU)

The distribution of the measurand is approximately normal ($\sim$ CLT)